# Asymptotic freedom in (3+1)-dimensional projectable Hořava gravity 

Alexander Kurov<br>Lebedev Physics Institute

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In collaboration with A. O. Barvinsky and S. M. Sibiryakov

## Motivation for Hořava gravity

Einstein GR

$$
\begin{equation*}
S_{E H}=\frac{M_{P}^{2}}{2} \int d t d^{d} x \sqrt{-g} R \Rightarrow \frac{M_{P}^{2}}{2} \int d t d^{d} x\left(h_{i j} \square h^{i j}+\ldots\right) \tag{1}
\end{equation*}
$$

Higher derivative gravity (Stelle 1977)

$$
\begin{equation*}
\int\left(R+R^{2}+R_{\mu \nu} R^{\mu \nu}\right) \Rightarrow \int\left(h_{i j} \square h^{i j}+h_{i j} \square^{2} h^{i j}+\ldots\right) \tag{2}
\end{equation*}
$$

The theory is renormalizable and asymptotically free. However the theory is not unitary due to presence of ghosts.

## Hořava gravity (2009)

The key is the anisotropic scaling of time and space coordinates,

$$
\begin{equation*}
t \mapsto b^{-z} t, \quad x^{i} \mapsto b^{-1} x^{i}, \quad i=1, \ldots, d \tag{3}
\end{equation*}
$$

The theory contains only second time derivatives

$$
\begin{equation*}
\int \underbrace{d t d^{d} x}_{\alpha b^{-(z+d)}}\left(\dot{h}_{i j} \dot{h}_{i j}-h_{i j}(-\Delta)^{z} h_{i j}+\ldots\right) \tag{4}
\end{equation*}
$$

And field scales as

$$
\begin{equation*}
h_{i j} \mapsto b^{(d-z) / 2} h_{i j} \tag{5}
\end{equation*}
$$

Critical theory

$$
\begin{equation*}
z=d \tag{6}
\end{equation*}
$$

Foliation preserving diffeomorphisms

$$
\begin{equation*}
t \mapsto t^{\prime}(t), \quad x^{i} \mapsto x^{\prime i}(t, \mathbf{x}) \tag{7}
\end{equation*}
$$

## Metric decomposition

The metric in the action of HG is expanded into the lapse $N$, the shift $N^{i}$ and the spatial metric $\gamma_{i j}$ like in the Arnowitt-Deser-Misner (ADM) decomposition,

$$
\begin{equation*}
\mathrm{d} s^{2}=N^{2} \mathrm{~d} t^{2}-\gamma_{i j}\left(\mathrm{~d} x^{i}+N^{i} \mathrm{~d} t\right)\left(\mathrm{d} x^{j}+N^{j} \mathrm{~d} t\right) \tag{8}
\end{equation*}
$$

Fields are assigned the following dimensions under the anisotropic scaling:

$$
\begin{equation*}
[N]=\left[\gamma_{i j}\right]=0, \quad\left[N^{i}\right]=d-1 . \tag{9}
\end{equation*}
$$

## Projectable version

A.Barvinsky, D.Blas, M.Herrero-Valea, S.Sibiryakov, C.Steinwachs (2016)

We consider projectable version of Hořava gravity. The lapse $N$ is restricted to be a function of time only, $N=N(t)$

$$
\begin{equation*}
S=\frac{1}{2 G} \int \mathrm{~d} t \mathrm{~d}^{d} x \sqrt{\gamma}\left(K_{i j} K^{i j}-\lambda K^{2}-\mathcal{V}\right) \tag{10}
\end{equation*}
$$

where

$$
\begin{equation*}
K_{i j}=\frac{1}{2}\left(\dot{\gamma}_{i j}-\nabla_{i} N_{j}-\nabla_{j} N_{i}\right) . \tag{11}
\end{equation*}
$$

The potential part $\mathcal{V}$ in $d=3$ reads,

$$
\begin{align*}
\mathcal{V}= & 2 \Lambda-\eta R+\mu_{1} R^{2}+\mu_{2} R_{i j} R^{i j} \\
& +\nu_{1} R^{3}+\nu_{2} R R_{i j} R^{i j}+\nu_{3} R_{j}^{i} R_{k}^{j} R_{i}^{k}+\nu_{4} \nabla_{i} R \nabla^{i} R+\nu_{5} \nabla_{i} R_{j k} \nabla^{i} R^{j k}, \tag{12}
\end{align*}
$$

This expression includes all relevant and marginal terms. It contains 9 couplings $\Lambda, \eta, \mu_{1}, \mu_{2}$ and $\nu_{a}, a=1, \ldots, 5$.

## Dispersion relations

The spectrum of perturbations contains a transverse-traceless graviton and a scalar mode. Both modes have positive kinetic terms when $G$ is positive and

$$
\begin{equation*}
\lambda<1 / 3 \text { or } \lambda>1 . \tag{13}
\end{equation*}
$$

Their dispersion relations around a flat background are

$$
\begin{align*}
& \omega_{t t}^{2}=\eta k^{2}+\mu_{2} k^{4}+\nu_{5} k^{6},  \tag{14a}\\
& \omega_{s}^{2}=\frac{1-\lambda}{1-3 \lambda}\left(-\eta k^{2}+\left(8 \mu_{1}+3 \mu_{2}\right) k^{4}\right)+\nu_{s} k^{6}, \tag{14b}
\end{align*}
$$

where $k$ is the spatial momentum and we have defined

$$
\begin{equation*}
\nu_{s} \equiv \frac{(1-\lambda)\left(8 \nu_{4}+3 \nu_{5}\right)}{1-3 \lambda} . \tag{15}
\end{equation*}
$$

These dispersion relations are problematic at low energies where they are dominated by the $k^{2}$-terms.

## One-loop action

Background field method with static background metric and zero background shift

$$
\begin{equation*}
\gamma_{i j}(\tau, \mathbf{x})=g_{i j}(\mathbf{x})+h_{i j}(\tau, \mathbf{x}), \quad N^{i}(\tau, \mathbf{x})=0+n^{i}(\tau, \mathbf{x}) . \tag{16}
\end{equation*}
$$

The one-loop effective action is given by the Gaussian path integral

$$
\exp \left(-\Gamma^{1-\text { loop }}\right)=\sqrt{\operatorname{Det} \mathcal{O}_{i j}} \int\left[d h^{A} d n^{i} d c^{i} d \bar{c}_{j}\right] \exp \left(-S^{(2)}\left[h^{A}, n^{i}, c^{i}, c_{j}\right]\right)
$$

where the quadratic part of the full action consists of three contributions metric, shift vector and ghost ones,

$$
\begin{align*}
S^{(2)}\left[h^{A}, n^{i}, c^{i}, \bar{c}_{j}\right] & =\frac{1}{G} \int d \tau d^{3} x \sqrt{g}\left[\frac{1}{2} h^{A}\left(-\mathbb{G}_{A B} \partial_{\tau}^{2}+\mathbb{D}_{A B}\right) h^{B}\right. \\
& \left.+\frac{1}{2} \sigma n^{i} \mathcal{O}_{i k}\left(-\delta_{j}^{k} \partial_{\tau}^{2}+\mathbb{B}_{j}^{k}\right) n^{j}+\bar{c}_{i}\left(-\delta_{j}^{i} \partial_{\tau}^{2}+\mathbb{B}_{j}^{i}\right) c^{j}\right] . \tag{17}
\end{align*}
$$

## Metric part of the action

The kinetic part for the metric perturbations has the form

$$
\begin{equation*}
-\frac{\sqrt{g}}{2 G} h^{A} \mathbb{G}_{A B} \partial_{\tau}^{2} h^{B}, \quad \mathbb{G}^{i j, k l}=\frac{1}{8}\left(g^{i k} g^{j l}+g^{i l} g^{j k}\right)-\frac{\lambda}{4} g^{i j} g^{k l}, \tag{18}
\end{equation*}
$$

where $h^{A} \equiv h_{i j}$. The part of the quadratic action with space derivatives of the metric is too lengthy to be written explicitly. Schematically, it has the form,

$$
\begin{equation*}
\mathcal{L}_{\text {pot }, \mathrm{hh}}+\mathcal{L}_{\mathrm{gf}, h h}=\frac{\sqrt{g}}{2 G} \underbrace{h^{A} \mathbb{D}_{A B} h^{B}}_{\approx 400 \text { terms }} \tag{19}
\end{equation*}
$$

where $\mathbb{D}_{A B}$ is a purely 3 -dimensional differential operator of 6 th order. In flat background it reduces to terms with exactly 6 derivatives,
$h^{A} \mathbb{D}_{A B} h^{B}=\left(\frac{\nu_{5}}{2}-\frac{1}{4 \sigma}\right) h^{i k} \Delta^{2} \partial_{i} \partial_{j} h^{j k}+\left(2 \nu_{4}+\frac{\nu_{5}}{2}+\frac{\lambda(1+\xi)}{2 \sigma}\right) h \Delta^{2} \partial_{k} \partial_{l} h^{k l}$
$-\left(\nu_{4}+\frac{\nu_{5}}{2}+\frac{\xi}{4 \sigma}\right) h^{i j} \Delta \partial_{i} \partial_{j} \partial_{k} \partial_{l} h^{k l}+\left(-\nu_{4}-\frac{\nu_{5}}{4}-\frac{\lambda^{2}(1+\xi)}{4 \sigma}\right) h \Delta^{3} h-\frac{\nu_{5}}{4} h^{i j} \Delta^{3} h_{i j}$.

## One-loop action and 3D reduction

Effective action consists of two parts

$$
\begin{equation*}
\Gamma^{1-\text { loop }}=\frac{1}{2} \operatorname{Tr} \ln \left(-\delta_{B}^{A} \partial_{\tau}^{2}+\mathbb{D}_{B}^{A}\right)-\frac{1}{2} \operatorname{Tr} \ln \left(-\delta_{j}^{i} \partial_{\tau}^{2}+\mathbb{B}^{i}{ }_{j}\right), \tag{20}
\end{equation*}
$$

where

$$
\begin{equation*}
\mathbb{D}_{B}^{A}=\left(\mathbb{G}^{-1}\right)^{A C} \mathbb{D}_{C B} \tag{21}
\end{equation*}
$$

The full one-loop action can be expressed as

$$
\begin{equation*}
\Gamma^{1-\text { loop }}=\frac{1}{2} \int d \tau\left[\operatorname{Tr}_{3} \sqrt{\mathbb{D}_{B}^{A}}-\operatorname{Tr}_{3} \sqrt{\mathbb{B}^{i}}{ }_{j}\right] . \tag{22}
\end{equation*}
$$

## The strategy for evaluation

The operators $\mathbb{F}=(\mathbb{D}, \mathbb{B})$ can be brought into the form:

$$
\begin{equation*}
\mathbb{F}=\sum_{a=0}^{6} \mathcal{R}_{(a)} \sum_{6 \geq 2 k \geq a} \alpha_{a, k} \nabla_{1} \ldots \nabla_{2 k-a}(-\Delta)^{3-k}, \quad \mathcal{R}_{(a)}=O\left(\frac{1}{l^{a}}\right) . \tag{23}
\end{equation*}
$$

Their square roots are nonlocal pseudo-differential operators given by

$$
\begin{equation*}
\sqrt{\mathbb{F}}=\sum_{a=0}^{\infty} \mathcal{R}_{(a)} \sum_{k \geq a / 2}^{K_{a}} \tilde{\alpha}_{a, k} \nabla_{1} \ldots \nabla_{2 k-a} \frac{1}{(-\Delta)^{k-3 / 2}} \tag{24}
\end{equation*}
$$

The UV divergent part of $\Gamma^{1 \text {-loop }}$ follows from the calculation of UFTs

$$
\begin{equation*}
\left.\int d^{3} x \mathcal{R}_{(a)}(\mathbf{x}) \nabla_{1} \ldots \nabla_{2 k-a} \frac{1}{(-\Delta)^{k-3 / 2}} \delta\left(\mathbf{x}, \mathbf{x}^{\prime}\right)\right|_{\mathbf{x}=\mathbf{x}^{\prime}} \tag{25}
\end{equation*}
$$

Since the divergences of HG have at maximum the dimensionality $a=6$, only finite number of such traces will be needed. The problem is split in two steps - calculation of the operator square root and the evaluation of UFTs.

## Perturbative scheme

Square root contains all powers of curvature. By denoting all curvature corrections in $\sqrt{\mathbb{F}}$ as $\mathbb{X}$,

$$
\begin{equation*}
\sqrt{\mathbb{F}}=\mathbb{Q}^{(0)}+\mathbb{X} \tag{26}
\end{equation*}
$$

one obtains the equation for this correction term

$$
\begin{equation*}
\mathbb{Q}^{(0)} \mathbb{X}+\mathbb{X} \mathbb{Q}^{(0)}=\mathbb{F}-\left(\mathbb{Q}^{(0)}\right)^{2}-\mathbb{X}^{2}, \quad \mathbb{F}-\left(\mathbb{Q}^{(0)}\right)^{2} \propto R . \tag{27}
\end{equation*}
$$

This nonlinear equation can be solved by iterations because its right hand side is at least linear in curvature.

## Universal functional traces

I.Jack and H.Osborn (1984), A.Barvinsky and G.Vilkovisky (1985)

$$
\left.\nabla_{i_{1} \ldots \nabla_{i_{p}}} \frac{\hat{1}}{(-\Delta)^{N+1 / 2}} \delta(x, y)\right|_{y=x}=\left.\frac{1}{\Gamma(N+1 / 2)} \nabla_{i_{1}} \ldots \nabla_{i_{p}} \int_{0}^{\infty} d s s^{N-1 / 2} \mathrm{e}^{s \Delta} \hat{\delta}(x, y)\right|_{y=x} ^{\mathrm{div}}
$$

Heat-kernel (Schwinger-DeWitt) expansion

$$
\mathrm{e}^{s \Delta} \hat{\delta}(x, y)=\frac{\mathcal{D}^{1 / 2}(x, y)}{(8 \pi)^{d / 2}} e^{-\frac{\sigma(x, y)}{2 s}} \sum_{n=0}^{\infty} s^{n} \hat{a}_{n}(x, y)
$$

Example of tensor UFTs

$$
\begin{aligned}
& \left.g^{i j}(-\Delta)^{1 / 2} \delta_{i j}{ }^{k l}(x, y)\right|_{y=x} ^{\operatorname{div}}=-\frac{\ln L^{2}}{16 \pi^{2}} \sqrt{g} g^{k l} \frac{1}{30}\left(\frac{1}{2} R^{m n} R_{m n}+\frac{1}{4} R^{2}+\Delta R\right), \\
& \left.\int d^{3} x \delta_{l}^{j} \nabla_{k} \nabla^{i}(-\Delta)^{1 / 2} \delta_{i j}^{k l}(x, y)\right|_{y=x} ^{\text {div }}
\end{aligned}
$$

$$
=-\frac{\ln L^{2}}{16 \pi^{2}} \int d^{3} x \sqrt{g}\left(-\frac{23}{80} R_{j}^{i} R_{k}^{j} R_{i}^{k}+\frac{753}{1120} R_{i j} R^{i j} R-\frac{22}{105} R^{3}-\frac{1}{84} R \Delta R-\frac{61}{560} R_{i j} \Delta R^{i j}\right)
$$

## Beta functions

Essential couplings

$$
\begin{align*}
& \mathcal{G}=\frac{G}{\sqrt{\nu_{5}}}, \quad \lambda, \quad u_{s}=\sqrt{\frac{(1-\lambda)\left(8 \nu_{4}+3 \nu_{5}\right)}{(1-3 \lambda) \nu_{5}}}, \quad v_{a}=\frac{\nu_{a}}{\nu_{5}}, \quad a=1,2,3,  \tag{28}\\
& \beta_{\lambda}=\mathcal{G} \frac{27(1-\lambda)^{2}+3 u_{s}(11-3 \lambda)(1-\lambda)-2 u_{s}^{2}(1-3 \lambda)^{2}}{120 \pi^{2}(1-\lambda)\left(1+u_{s}\right) u_{s}},  \tag{29a}\\
& \beta_{\mathcal{G}}=\frac{\mathcal{G}^{2}}{26880 \pi^{2}(1-\lambda)^{2}(1-3 \lambda)^{2}\left(1+u_{s}\right)^{3} u_{s}^{3}} \sum_{n=0}^{7} u_{s}^{n} \mathcal{P}_{n}^{\mathcal{G}}\left[\lambda, v_{1}, v_{2}, v_{3}\right],  \tag{29b}\\
& \beta_{\chi}=A_{\chi} \frac{\mathcal{G}}{26880 \pi^{2}(1-\lambda)^{3}(1-3 \lambda)^{3}\left(1+u_{s}\right)^{3} u_{s}^{5}} \sum_{n=0}^{9} u_{s}^{n} \mathcal{P}_{n}^{\chi}\left[\lambda, v_{1}, v_{2}, v_{3}\right], \tag{29c}
\end{align*}
$$

where the prefactor coefficients $A_{\chi}=\left(A_{u_{s}}, A_{v_{1}}, A_{v_{2}}, A_{v_{3}}\right)$ equal

$$
\begin{equation*}
A_{u_{s}}=u_{s}(1-\lambda), \quad A_{v_{1}}=1, \quad A_{v_{2}}=A_{v_{3}}=2 \tag{30}
\end{equation*}
$$

Example of a polynomial

$$
\begin{aligned}
& \mathcal{P}_{2}^{u_{s}}=-2(1-\lambda)^{3}\left[2419200 v_{1}^{2}(1-\lambda)^{2}+8 v_{2}^{2}\left(42645 \lambda^{2}-86482 \lambda+43837\right)\right. \\
& +v_{3}^{2}\left(58698-106947 \lambda+48249 \lambda^{2}\right)+4032 v_{1}\left(462 v_{2}(1-\lambda)^{2}+201 v_{3}(1-\lambda)^{2}\right. \\
& \left.+30 \lambda^{2}-44 \lambda-10\right)+8 v_{2}\left(6252 \lambda^{2}-9188 \lambda-1468\right)+8 v_{2} v_{3}\left(34335 \lambda^{2}-71196 \lambda\right. \\
& \left.+36861)+v_{3}\left(20556 \lambda^{2}-30792 \lambda-3696\right)+4533 \lambda^{2}-3881 \lambda+1448\right]
\end{aligned}
$$

## Fixed points of RG flow

There are 5 solutions for the system of equations

$$
\begin{equation*}
\beta_{g_{i}}=0, \quad g_{i}=\lambda, u_{s}, v_{1}, v_{2}, v_{3} . \tag{31}
\end{equation*}
$$

They written down in the table

| $\lambda$ | $u_{s}$ | $v_{1}$ | $v_{2}$ | $v_{3}$ | $\beta_{\mathcal{G}} / \mathcal{G}^{2}$ | AF? |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0.1787 | 60.57 | -928.4 | -6.206 | -1.711 | -0.1416 | yes |
| 0.2773 | 390.6 | -19.88 | -12.45 | 2.341 | -0.2180 | yes |
| 0.3288 | 54533 | $3.798 \times 10^{8}$ | -48.66 | 4.736 | -0.8484 | yes |
| 0.3289 | 57317 | $-4.125 \times 10^{8}$ | -49.17 | 4.734 | -0.8784 | yes |
| 0.333332 | $3.528 \times 10^{11}$ | $-6.595 \times 10^{23}$ | $-1.950 \times 10^{8}$ | 4.667 | $-3.989 \times 10^{6}$ | yes |

Invariance of GR under 4 d diffeomorphisms sets the value of $\lambda$ to 1 . That's why one expects that $\lambda \rightarrow 1^{+}$in the IR limit. However, all the solutions lie on the left side of the unitary domain

$$
\begin{equation*}
\lambda<1 / 3 \text { or } \lambda>1 \tag{32}
\end{equation*}
$$

and there are no RG trajectories with $\lambda \rightarrow 1^{+}$.

## $\lambda \rightarrow \infty$ limit

A.Gümrükçüoğlu and S.Mukohyama, Rev. D 83 (2011) 124033

The beta function $\beta_{\lambda}$ diverges in the limit $\lambda \rightarrow \infty$. For the new variable $\varrho$, the limit $\lambda=\infty$ corresponds to the finite $\varrho=1$. It's beta function reads

$$
\begin{equation*}
\beta_{\varrho}=3(1-\varrho) \mathcal{G} \frac{2 u_{s}^{2}+u_{s} \varrho(4-5 \varrho)-3 \varrho^{2}}{40 \pi^{2} u_{s}\left(1+u_{s}\right) \varrho}, \quad \varrho \equiv 3 \frac{1-\lambda}{1-3 \lambda} . \tag{33}
\end{equation*}
$$

Solutions of the system

$$
\begin{equation*}
\beta_{\chi} /\left.\mathcal{G}\right|_{\substack{\lambda=\infty \\(\varrho=1)}}=0, \quad \chi=u_{s}, v_{1}, v_{2}, v_{3} . \tag{34}
\end{equation*}
$$

are written down in the table

| № | $u_{s}$ | $v_{1}$ | $v_{2}$ | $v_{3}$ | $\beta_{\mathcal{G}} / \mathcal{G}^{2}$ | AF? | Can flow <br> out of $\varrho=1 ?$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | 0.0195 | 0.4994 | -2.498 | 2.999 | -0.2004 | yes | no |
| 2 | 0.0418 | -0.01237 | -0.4204 | 1.321 | -1.144 | yes | no |
| 3 | 0.0553 | -0.2266 | 0.4136 | 0.7177 | -1.079 | yes | no |
| 4 | 12.28 | -215.1 | -6.007 | -2.210 | -0.1267 | yes | yes |
| 5 (A) | 21.60 | -17.22 | -11.43 | 1.855 | -0.1936 | yes | yes |
| 6 (B) | 440.4 | -13566 | -2.467 | 2.967 | 0.05822 | no | yes |
| 7 | 571.9 | -9.401 | 13.50 | -18.25 | -0.0745 | yes | yes |
| 8 | 950.6 | -61.35 | 11.86 | 3.064 | 0.4237 | no | yes |

## Stability matrix

In the vicinity of a fixed point, the linearized RG flow can be analyzed with the help of the stability matrix $B_{i}{ }^{j}$,

$$
\begin{equation*}
\tilde{\beta}_{g_{i}} \cong \sum_{j} B_{i}^{j}\left(g_{j}-g_{j}^{*}\right),\left.\quad B_{i}^{j} \equiv\left(\frac{\partial \tilde{\beta}_{g_{i}}}{\partial g_{j}}\right)\right|_{g_{i}=g_{i}^{*}}, \quad \tilde{\beta}_{g_{i}}=\beta_{g_{i}} / \mathcal{G} \tag{35}
\end{equation*}
$$

where $g_{i}^{*}$ are fixed point values of the coupling constants.

| Fixed point | $\theta^{1}$ | $\theta^{2}$ | $\theta^{3}$ | $\theta^{4}$ | $\theta^{5}$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| A | -0.0141 | -0.0700 | 0.257 | 0.320 | 0.0657 |
| B | -0.0151 | 0.603 | 0.308 | $0.092 \pm 0.289 i$ |  |

Table: Eigenvalues $\theta^{I}$ of the stability matrix for the fixed points A and B .

## RG equation

We choose as an initial condition of the RG equation a point slightly shifted from the fixed point $g^{*}$ in the repulsive direction

$$
\left\{\begin{array}{l}
\frac{d g_{i}}{d \tau}=\tilde{\beta}_{g_{i}}, \quad g_{i}=\left(v_{1}, v_{2}, v_{3}, u_{s}, \varrho\right)  \tag{36}\\
g_{i}(0)=g_{i}^{*}+\varepsilon c_{J} w_{i}^{J}, \quad J=1,2,3,4,5 .
\end{array}\right.
$$

where $\varepsilon$ is a small parameter, $c_{J}$ are constants and $w_{i}^{J}$ are eigenvectors enumerated by the index $J, B_{i}{ }^{j} w_{j}^{J}=\theta^{J} w_{i}^{J}$, with $\theta^{J}<0$.

| Eigen- <br> vector | $w_{\varrho}$ | $w_{v_{1}}$ | $w_{v_{2}}$ | $w_{v_{3}}$ | $w_{u_{s}}$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $A 1$ | 0.0423 | -0.0398 | $5.25 \times 10^{-3}$ | $5.57 \times 10^{-3}$ | 0.998 |
| $A 2$ | 0 | -0.115 | -0.224 | 0.0480 | -0.967 |
| $B 1$ | $2.19 \times 10^{-5}$ | -0.999 | $1.87 \times 10^{-5}$ | $5.69 \times 10^{-6}$ | 0.0162 |

Table: Eigenvectors of the stability matrix with negative eigenvalues for the fixed points A and B.

## From A to B

First we build the trajectory flowing from point A along the eigenvector $A 2$. Since this vector has zero $\varrho$-part, the trajectory stays in the hyperplane $\varrho=1$.



Figure: RG trajectory connecting fixed points A and B. The trajectory lies entirely in the hyperplane $\varrho=1$. Panels show its projections on the $\left(u_{s}, v_{1}\right)$ and $\left(v_{2}, v_{3}\right)$ planes. Arrows indicate the flow from UV to IR.

## From B to $\lambda \rightarrow 1^{+}$

Point B has a unique repulsive direction, pointing away from the $\varrho=1$ hyperplane. This gives rise to two RG trajectories, depending on the sign of $\varepsilon$ in the initial conditions.


Figure: The couplings $\left(u_{s}, v_{a}\right)$ as functions of $\varrho$ along the RG trajectory from the fixed point B to $\varrho=0\left(\lambda \rightarrow 1^{+}\right)$. Arrows indicate the flow from UV to IR.

## The behaviour of $\mathcal{G}$



Figure: Behaviour of $\mathcal{G}$ as a function of $(\lambda-1)$ along an RG trajectory connecting the point A to $\lambda \rightarrow 1^{+}$. In regions $I, I I$ and $I I I$ the dependence is well described by the power law $\mathcal{G} \propto(\lambda-1)^{k}$ with $k_{I}=-13.69, k_{I I}=3.84, k_{I I I} \approx 0.37$.

## Conclusions

- Beta functions for all essential coupling in (3+1)-dimensional Hořava gravity were obtained.
- The results underwent a number of very powerful checks.
- All the fixed points of RG flow were found.
- A family of trajectories was found. They are connecting AF fixed point in the UV to the region where the kinetic term has GR form.

